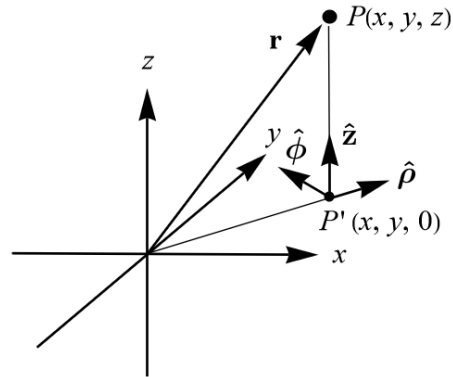


Problem 1.48

Find expressions for the unit vectors $\hat{\rho}$, $\hat{\phi}$, and \hat{z} of cylindrical polar coordinates (Problem 1.47) in terms of the Cartesian \hat{x} , \hat{y} , \hat{z} . Differentiate these expressions with respect to time to find $d\hat{\rho}/dt$, $d\hat{\phi}/dt$, and $d\hat{z}/dt$.

Solution

The unit vectors in cylindrical coordinates (ρ, ϕ, z) are illustrated below.



$\hat{\rho}$ points radially outward from the z -axis; $\hat{\phi}$ is perpendicular to both $\hat{\rho}$ and \hat{z} , pointing in the direction of increasing ϕ ; and \hat{z} points in the direction of the z -axis.

$$\begin{aligned}
 \hat{\rho} &= \frac{\boldsymbol{\rho}}{|\boldsymbol{\rho}|} \\
 &= \frac{x \hat{\mathbf{x}} + y \hat{\mathbf{y}} + 0 \hat{\mathbf{z}}}{\sqrt{x^2 + y^2 + 0^2}} \\
 &= \frac{x}{\sqrt{x^2 + y^2}} \hat{\mathbf{x}} + \frac{y}{\sqrt{x^2 + y^2}} \hat{\mathbf{y}} + 0 \hat{\mathbf{z}} \\
 &= \frac{x}{\rho} \hat{\mathbf{x}} + \frac{y}{\rho} \hat{\mathbf{y}} + 0 \hat{\mathbf{z}} \\
 &= \cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} + 0 \hat{\mathbf{z}} \\
 \hat{\phi} &= \hat{\mathbf{z}} \times \hat{\rho} \\
 &= \hat{\mathbf{z}} \times (\cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} + 0 \hat{\mathbf{z}}) \\
 &= \cos \phi (\hat{\mathbf{z}} \times \hat{\mathbf{x}}) + \sin \phi (\hat{\mathbf{z}} \times \hat{\mathbf{y}}) + 0 (\hat{\mathbf{z}} \times \hat{\mathbf{z}}) \\
 &= \cos \phi (\hat{\mathbf{y}}) + \sin \phi (-\hat{\mathbf{x}}) + 0 (\mathbf{0}) \\
 &= -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} + 0 \hat{\mathbf{z}} \\
 \hat{\mathbf{z}} &= \hat{\mathbf{z}}
 \end{aligned}$$

Take the first derivative of each cylindrical unit vector with respect to t , noting that the derivative of each Cartesian unit vector with respect to time is zero.

$$\begin{aligned}
 \frac{d\hat{\rho}}{dt} &= \frac{d}{dt}(\cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} + 0 \hat{\mathbf{z}}) \\
 &= \frac{d}{dt}(\cos \phi \hat{\mathbf{x}}) + \frac{d}{dt}(\sin \phi \hat{\mathbf{y}}) \\
 &= \frac{d}{dt}(\cos \phi) \hat{\mathbf{x}} + \cos \phi \frac{d\hat{\mathbf{x}}}{dt} + \frac{d}{dt}(\sin \phi) \hat{\mathbf{y}} + \sin \phi \frac{d\hat{\mathbf{y}}}{dt} \\
 &= \left(-\sin \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{x}} + \cos \phi \underbrace{\frac{d\hat{\mathbf{x}}}{dt}}_{= \mathbf{0}} + \left(\cos \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{y}} + \sin \phi \underbrace{\frac{d\hat{\mathbf{y}}}{dt}}_{= \mathbf{0}} \\
 &= \left(-\sin \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{x}} + \left(\cos \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{y}} \\
 &= \frac{d\phi}{dt}(-\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}}) \\
 &= \frac{d\phi}{dt} \hat{\phi}
 \end{aligned}$$

$$\begin{aligned}
 \frac{d\hat{\phi}}{dt} &= \frac{d}{dt}(-\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} + 0 \hat{\mathbf{z}}) \\
 &= \frac{d}{dt}(-\sin \phi \hat{\mathbf{x}}) + \frac{d}{dt}(\cos \phi \hat{\mathbf{y}}) \\
 &= \frac{d}{dt}(-\sin \phi) \hat{\mathbf{x}} - \sin \phi \frac{d\hat{\mathbf{x}}}{dt} + \frac{d}{dt}(\cos \phi) \hat{\mathbf{y}} + \cos \phi \frac{d\hat{\mathbf{y}}}{dt} \\
 &= \left(-\cos \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{x}} - \sin \phi \underbrace{\frac{d\hat{\mathbf{x}}}{dt}}_{= \mathbf{0}} + \left(-\sin \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{y}} + \cos \phi \underbrace{\frac{d\hat{\mathbf{y}}}{dt}}_{= \mathbf{0}} \\
 &= \left(-\cos \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{x}} + \left(-\sin \phi \cdot \frac{d\phi}{dt}\right) \hat{\mathbf{y}} \\
 &= -\frac{d\phi}{dt}(\cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}}) \\
 &= -\frac{d\phi}{dt} \hat{\rho}
 \end{aligned}$$

$$\frac{d\hat{\mathbf{z}}}{dt} = \mathbf{0}$$

Therefore,

$$\frac{d\hat{\rho}}{dt} = \frac{d\phi}{dt} \hat{\phi} \quad \text{and} \quad \frac{d\hat{\phi}}{dt} = -\frac{d\phi}{dt} \hat{\rho} \quad \text{and} \quad \frac{d\hat{\mathbf{z}}}{dt} = \mathbf{0}.$$